

Figure 1. PolyMapper HS 360

**PolyMapper HS** is a state-of-the-art mobile mapping system for HD maps. It boasts a high performance 360° LiDAR, a front view industrial camera and a tightly-coupled GNSS/INS with an optional panoramic camera for different market needs. With the foldable antenna arms, it is designed for easy installation on automotive vehicles by a single person.

Integrated with a GPU, the PolyMapper HS features georeferenced 3D point cloud generation in real time. With the built-in RTK engine, it can achieve centimeter level accuracy in real time. A cloud-based HD map platform and an Al-based feature extraction software are postprocessing add-ons. They enable users to create and edit map data in streamlined workflow and export map data in various formats.

#### **FEATURES**

- Front view industrial camera with global shutter
- Dual GNSS antennas with foldable antenna arms
- 3D point cloud at large scale
- Georeferenced 3D point cloud at centimeter-level accuracy in real time
- Customizable internal data storage, 2 TB by default
- Support accessories: USB, Ethernet, PPS, CAN, UART, DMI
- System options
  - PolyMapper HS (Figure 2)
  - PolyMapper HS 360 (Figure 1, panoramic camera integrated)



Figure 2. PolyMapper HS, antenna arms folded

#### SOFTWARE

- Easy to use control software PolyScanner, compatible with tablet and PC
- Post-processing software
  - · 3D cloud point generation
  - · Noise suppression unit, automatic colorization
  - · Georeferenced LAS file, imagery, trajectory and status
- Optional post-processing software
  - · Al-based feature extraction software
  - · Could-based HD map platform



#### **APPLICATIONS**

- High precision map collection

- Road Asset Management

- Robotics

Urban data acquisition

- Smart transportation



Visit www.polyexplore.com for more information.

# **SYSTEM SPECIFICATIONS**

# MOBILE HD MAPPING SYSTEM PolyMapper HS

#### **LiDAR**

| Range                   | 0.05 to 120 m  |
|-------------------------|--|
| Range Capability        | 80 m @10% reflectivity (Channels 5 -12)<br>50 m @10% (Channels 1 to 4, 13, 16) |
| Range Accuracy          | ±1 cm (typical)<br>±2 cm (standard)  |
| Range Precision         | 0.5 cm (typical, 1σ)<br>2 cm (standard)  |
| FOV (Horizontal)        | 360°   |
| Resolution (Horizontal) | 0.09° (5 Hz), 0.18° (10 Hz), 0.36° (20 Hz)                                     |
| FOV (Vertical)          | 30° (-15° to +15°)   |
| Resolution (Vertical)   | 2°   |
| Frame Rate              | 5 Hz, 10 Hz, 20 Hz   |
| Returns                 | Single Return (Last, Strongest, First)  Dual Return                            |

#### **GNSS/INS**

| Constellations    | GPS/GLONASS/Beidou/Galileo |
|-------------------|----------------------------|
| Satellite Signals | L1, L2, L5                 |
| Measurement Rate  | 100 Hz                     |
| Accuracy          |                            |
| Position          | 1.5 m CEP SPS, 0.02 m RTK  |
| Velocity          | 0.03 m/s                   |
| Pitch/Roll        | 0.005°                     |
| Heading           | 0.03°                      |

## **PANORAMIC CAMERA**

| Resolution        | 7680 x 3840 (8K) |
|-------------------|------------------|
| Frame Rate        | Up to 30 fps     |
| Photo File Format | JPEG/DNG         |

### **FRONT VIEW CAMERA**

| Shutter Type  | Global Shutter |
|---------------|----------------|
| Resolution    | 2448 x 2048    |
| Dynamic Range | 72 dB          |

# PHYSICAL, ENVIRONMENTAL & ELECTRICAL

| Ingress     | IP67  |
|-------------|---|
| Weight      | 5.10 kg (panoramic camera not included)<br>7.15 kg (panoramic camera included)                                |
| Dimensions  | 310 mm x 230 mm x 175 mm (panoramic camera not included) 310 mm x 230 mm x 425 mm (panoramic camera included) |
| Temperature | -20°C to +40°C Operation<br>-20°C to +50°C Storage  |
| Power       | 12 VDC  |

